Slides available:

http://www.ibis.t.u-tokyo.ac.jp/ryotat/tensor12kyoto.pdf

Statistical Performance of Convex Tensor Decomposition

Ryota Tomioka 2012/01/26 @ Kyoto University Perspectives in Informatics 4B

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Netflix challenge (2006-2009)

- \$1,000,000 prize
- Goal: Improve the performance of a video recommendation system

(predict who likes which movies)

• Example:



Likes "Star Wars" and "E.T.", Doesn't like "Minority Report".

Does he like "Blade Runner"?

Matrix completion view



User A	+1	+1	-1	?	?
User B	+1	?	?	+1	?
User C	?	+1	-1	?	+1
User D	+1	?	?	?	+1
	•	•	·	·	•
	•	•	·	·	•

Goal: fill the missing entries!

Matrix completion

- Impossible without an assumption. (Missing entries can be arbitrary) --- problem is ill-posed
- Most common assumption:





Matrix completion

• Most common assumption:



Geometric Intuition

r-dimensional space

(r: the rank of the decomposition)



Geometric Intuition

r-dimensional space

(r: the rank of the decomposition)



Tensor data completion

- Tensor = Multi-dimensional array
- Beyond 2D

Movie preference + time / context / action





Tensor data completion

- Tensor = Multi-dimensional array
- Beyond 2D

Climate monitoring

- temperature
- humidity
- rainfall





Tensor data completion

- Tensor = Multi-dimensional array
- Time Beyond 2D Sensors Neuroscience (brain imaging) Time subjects ons Sensors

Rest of this talk

- Computing low-rank matrix decomposition
- Generalizing from matrix to tensor
- Analyzing the performance
 - Statistical learning theory

Computing low-rank matrix decomposition

Computing low-rank decomposition

- If all entries are observed (no missing entries)
 - Given Y, compute singular value decomposition (SVD)

$$m \underbrace{\mathbf{Y}}_{\mathbf{Y}} \stackrel{\mathbf{r}}{\rightleftharpoons} m \underbrace{\mathbf{U}}_{\mathbf{U}} \stackrel{\mathbf{r}}{\mathbf{\Sigma}} r \underbrace{\mathbf{V}}_{\mathbf{V}}$$

where U, V: Orthogonal ($U^TU=I$, $V^TV=I$)

$$\boldsymbol{\Sigma} = \begin{pmatrix} \sigma_1 & & \\ & \ddots & \\ & & \sigma_r \end{pmatrix}$$

 σ_j : jth largest singular value







Convex relaxation of rank

Schatten *p*-norm (to the *p*th power)

$$\begin{split} \mathbf{W} \|_{S_p}^p &:= \sum_{j=1}^r \sigma_j^p(\mathbf{W}) \\ \sigma_j(\mathbf{W}) &: j \text{th largest singular value} \end{split}$$

$$\|W\|_{S_p}^p \xrightarrow{p \to 0} \operatorname{rank}(W)$$

lxl^{0.01} p=1 is the tightest lxl^{0.5} lxl 3 x² convex relaxation 2 (also known as trace norm / nuclear norm 0^L -3 -2 -1 2 3 0 1



Cf. Lasso (L_1 norm) for variable selection = linear sum of abs. coefficients

Take home messages

- Rank constrained minimization is hard to solve (non-convex and NP hard)
- Can be relaxed into a tractable convex problem using Schatten 1-norm.

How about tensors?

- How to define tensor rank?
- How related to matrix rank?

Ranf of a tensor

Definition. Let $\mathcal{X} \in \mathbb{R}^{n_1 \times \cdots \times n_K}$ (*K*th order tensor)

The smallest number R such that the given tensor X is written as



- Called CP (CANDECOMPO/PARAFAC) decomposition
- Bad news: NP hard to compute the rank R even for a fully observed X.

Bad news 2: Tensor rank is not closed



Tucker decomposition [Tucker 66]



- Also known as higher-order SVD [De Lathauwer+00]
- Rank (r_1, r_2, r_3) can be computed in polynomial time using unfolding operations.

Mode-k unfoldings (matricization)



 $n_3 \cdot n_1$

Computing Tucker rank

- For each k=1,...,K
 - Compute the mode-k unfolding $X_{(k)}$
 - Compute the (matrix) rank of $\mathbf{X}_{\mathrm{(k)}}$ $r_k = \mathrm{rank}(\boldsymbol{X}_{(k)})$



Computing Tucker rank

- For each k=1,...,K
 - Compute the mode-k unfolding $X_{(k)}$
 - Compute the (matrix) rank of $X_{(k)}$

$$r_k = \operatorname{rank}(X_{(k)})$$

- Difference between Tensor rank and Tucker rank
 - Tensor rank is a single number R (may not be easy to compute)
 - Tucker rank is defined for each mode (easy to compute)
- CP decomp is a special case of Tucker decomp with
 R=r₁=r₂=...=r_κ and diagonal core

C =

Basic idea

- We know how to do matrix completion with Schatten 1-norm (tractable convex optimization)
- We know how to compute Tucker rank (=the rank of the mode-k unfolding)



Overlapped Schatten 1-norm for Tensors



Measures the overall low-rank-ness

(not just a single mode)

Convex Tensor Estimation

Matrix

Estimation of *lowrank* matrix (hard)



Tensor Estimation of *lowrank* tensor (hard)



Schatten 1-norm minimization (tractable) [Fazel, Hindi, Boyd 01] Generalize **Overlapped** Schatten 1-norm minimization [Liu+09, Signoretto+10, Tomioka+10, Gandy+11]

Empirical performance

Tensor completion result [Tomioka et al. 2010]

size=50x50x20, rank=7x8x9 (No noise) Convex Error IIW*–W^{AII}_F EM (nonconvex) 10⁰ Optimization tolerance 10⁻³ 0.1 0.2 0.3 0.4 0.5 0.6 0.8 0.9 0 0.7 Fraction of observed elements $M/(n_1n_2n_3)$ Phase transition!!

Can we predict this theoretically?

Analyzing the performance of convex tensor decomposition

Observation model

$$y_i = \langle \boldsymbol{\mathcal{X}}_i, \boldsymbol{\mathcal{W}}^* \rangle + \epsilon_i \quad (i = 1, \dots, M)$$

 \mathcal{W}^* true tensor rank-(r₁,...,r_K)

 ϵ_i Gaussian noise

Example (tensor completion)



Observation model

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Example (tensor completion)



Observation model

$$y_i = \langle \boldsymbol{\mathcal{X}}_i, \boldsymbol{\mathcal{W}}^* \rangle + \epsilon_i \quad (i = 1, \dots, M)$$

 \mathcal{W}^* true tensor rank-($r_1,...,r_K$)

 ϵ_i Gaussian noise

Example (tensor completion)



and so on...


Analysis objective

• We would like to show something like



The size $\mathbf{n} = (n_1, \dots, n_K)$ The rank $\mathbf{r} = (r_1, \dots, r_K)$ Number of samples M

Theorem: random Gauss design

Assume elements of X_i are drown iid from standard normal distribution. Moreover

$$\frac{\#\mathsf{samples}(M)}{\#\mathsf{variables}(N)} \geq c_1 \|n^{-1}\|_{1/2} \|r\|_{1/2} \approx \frac{r}{n}$$
Normalized rank

$$\|\boldsymbol{n}^{-1}\|_{1/2} := \left(\frac{1}{K} \sum_{k=1}^{K} \sqrt{1/n_k}\right)^2, \quad \|\boldsymbol{r}\|_{1/2} := \left(\frac{1}{K} \sum_{k=1}^{K} \sqrt{r_k}\right)^2$$



Proof idea



What we want to derive:

$$\frac{\left\| \widehat{\mathcal{W}} - \mathcal{W}^* \right\|_F^2}{N} \le O_p \left(\frac{c(\boldsymbol{n}, \boldsymbol{r})}{M} \right)$$

Proof outline (1/3)

Estimated tensor $\begin{aligned}
& \text{True low-rank tensor} \\
& \frac{1}{2M} \| \mathfrak{X}(\hat{\mathcal{W}} - \mathcal{W}^*) \|_2^2 \leq \left\langle \mathfrak{X}^*(\epsilon) / M, \hat{\mathcal{W}} - \mathcal{W}^* \right\rangle + \lambda_M \left\| \hat{\mathcal{W}} - \mathcal{W}^* \right\|_{S_1}
\end{aligned}$

Inequality 1: upper-bound the dot product

$$\left\langle \mathfrak{X}^{*}(\boldsymbol{\epsilon})/M, \widehat{\mathcal{W}} - \mathcal{W}^{*} \right\rangle \leq O_{p} \left(\sqrt{\frac{\sigma^{2} N \|\boldsymbol{n}^{-1}\|_{1/2}}{M}} \left\| \widehat{\mathcal{W}} - \mathcal{W}^{*} \right\|_{S_{1}} \right)$$

(optimization duality / random matrix theory)

Proof outline (1/3)



Inequality 1: upper-bound the dot product

$$\left\langle \mathfrak{X}^{*}(\boldsymbol{\epsilon})/M, \widehat{\mathcal{W}} - \mathcal{W}^{*} \right\rangle \leq O_{p} \left(\sqrt{\frac{\sigma^{2} N \|\boldsymbol{n}^{-1}\|_{1/2}}{M}} \left\| \widehat{\mathcal{W}} - \mathcal{W}^{*} \right\|_{S_{1}} \right)$$

Trade-off between $\sqrt{\frac{\sigma^2 N \| \boldsymbol{n}^{-1} \|_{1/2}}{M}}$ and λ_M \bigwedge Optimal reg. const $\lambda_M \simeq O_p \left(\sqrt{\frac{\sigma^2 N \| \boldsymbol{n}^{-1} \|_{1/2}}{M}} \right)$

Proof outline (2/3)



Inequality 2: relate the schatten 1-norm with the Frobenius norm $\|\widehat{\mathcal{W}} - \mathcal{W}^*\|_{S_1} \leq \sqrt{\|r\|_{1/2}} \|\widehat{\mathcal{W}} - \mathcal{W}^*\|_F$

(relation between L1- and L2-norm)

Proof outline (2/3)



Inequality 2: relate the schatten 1-norm with the Frobenius norm $\|\widehat{\mathcal{W}} - \mathcal{W}^*\|_{S_1} \leq \sqrt{\|r\|_{1/2}} \|\widehat{\mathcal{W}} - \mathcal{W}^*\|_F$

(relation between L1- and L2-norm)

Proof outline (3/3)



Inequality 3: lower-bound the left hand-side $\kappa \| \widehat{\mathcal{W}} - \mathcal{W}^* \|_F^2 \leq \frac{1}{M} \| \widehat{\mathcal{X}} (\widehat{\mathcal{W}} - \mathcal{W}^*) \|_2^2$ If $\frac{\# \text{samples } (M)}{\# \text{variables } (N)} \geq c_1 \| \boldsymbol{n}^{-1} \|_{1/2} \| \boldsymbol{r} \|_{1/2}$

(Gordon-Slepian Theorem in Gaussian process theory)

Proof outline (3/3)

Estimated tensor True low-rank tensor $\kappa \| \hat{\mathcal{W}} - \mathcal{W}^* \|_F^2 \leq \sqrt{\frac{\sigma^2 N \| \boldsymbol{n}^{-1} \|_{1/2} \| \boldsymbol{r} \|_{1/2}}{M} \| \hat{\mathcal{W}} - \mathcal{W}^* \|_F$

> Inequality 3: lower-bound the left hand-side $\kappa \| \widehat{\mathcal{W}} - \mathcal{W}^* \|_F^2 \leq \frac{1}{M} \| \widehat{\mathcal{X}} (\widehat{\mathcal{W}} - \mathcal{W}^*) \|_2^2$ #samples (M)

If
$$\frac{\#\text{samples (M)}}{\#\text{variables (N)}} \ge c_1 \|\boldsymbol{n}^{-1}\|_{1/2} \|\boldsymbol{r}\|_{1/2}$$

(Gordon-Slepian Theorem in Gaussian process theory)

Back to the theorem statement

Assume elements of X_i are drown iid from standard normal distribution. Moreover

$$\frac{\#\text{samples }(M)}{\#\text{variables }(N)} \ge c_1 \|n^{-1}\|_{1/2} \|r\|_{1/2} \approx \frac{r}{n}$$

Normalized rank
Convergence!
$$\frac{\|\hat{\mathcal{W}} - \mathcal{W}^*\|_F^2}{N} \le O_p \left(\frac{\sigma^2 \|n^{-1}\|_{1/2} \|r\|_{1/2}}{M}\right)$$
$$\|n^{-1}\|_{1/2} := \left(\frac{1}{K} \sum_{k=1}^K \sqrt{1/n_k}\right)^2, \quad \|r\|_{1/2} := \left(\frac{1}{K} \sum_{k=1}^K \sqrt{r_k}\right)^2$$

Notice:

- Sample-size condition independent of noise σ^2 .
- Bound RHS proportional to σ^2 .

Threshold behavior in the limit $\sigma^2 \rightarrow 0$

Tensor completion results







Tensor completion *easier* than matrix completion!?

Conclusion

- Many real world problems can be cast into the form of tensor data analysis.
- Convex optimization is a useful tool also for the analysis of higher order tensors.
- Proposed a convex tensor decomposition algorithm with performance guarantee
- Normalized rank predicts empirical scaling behavior well

Issues

- Why matrix completion more difficult than tensor completion?
- How big the gap between necessity and sufficiency?
- Random Gaussian design ≠ tensor completion
 - \Rightarrow Incoherence (Candes & Recht 09)
 - \Rightarrow Spikiness (Negahban et al 10)
- When only some modes are low-rank
 - Schatten 1-norm is too strong \Rightarrow Mixture approach
 - E.g. Mode 1, 4 is low rank but the rest is not (combinatorial problem)

Thank vou