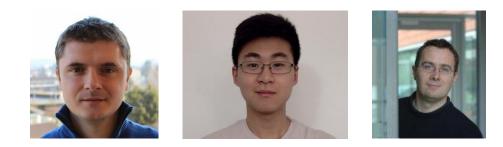
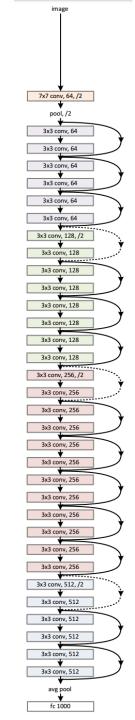
Quantized Stochastic Gradient Descent: Communication vs. Convergence

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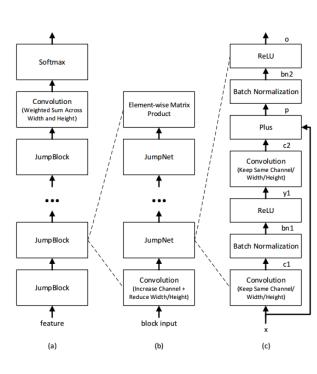
Deep models: how to train them efficiently?

• Vision

- ImageNet: 1.6 million images
- ResNet-152 [He+15]: 152 layers, 60 million parameters
- Speech
 - NIST2000 Switchboard dataset: 2000 hours
 - LACEA [Yu+16]: 22 layers, 65 million parameters (w/o language model)

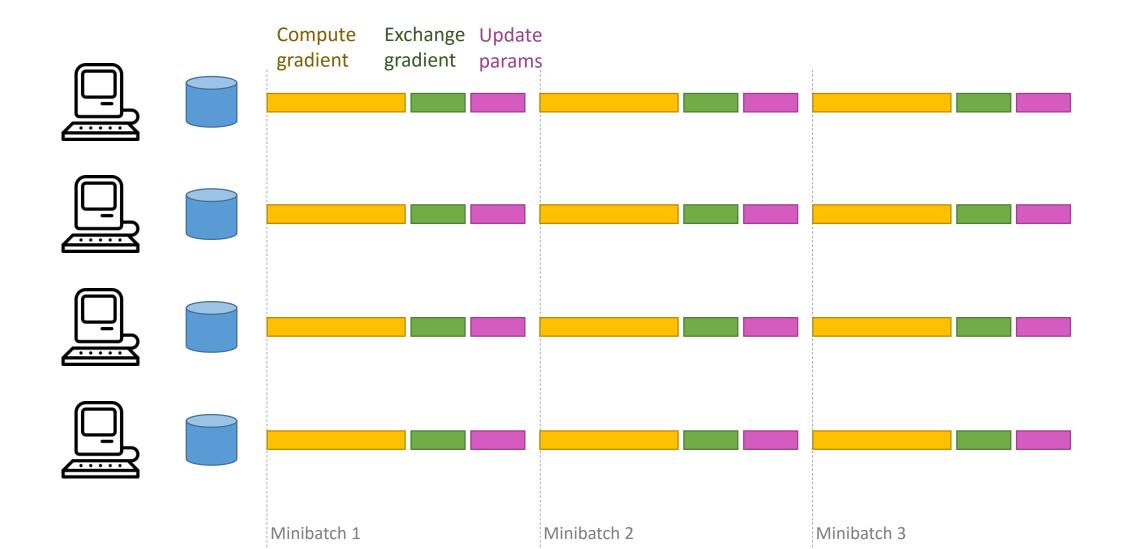
He et al. (2015) "Deep Residual Learning for Image Recognition"

Yu et al. (2016) "Deep convolutional neural networks with layer-wise context expansion and attention"

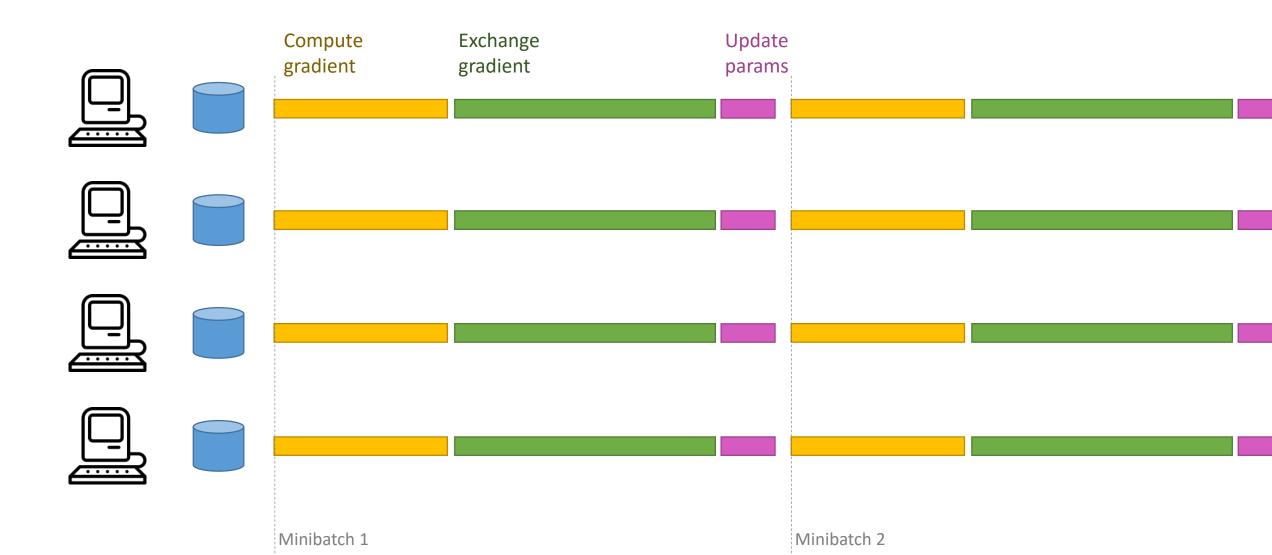


IM GENET

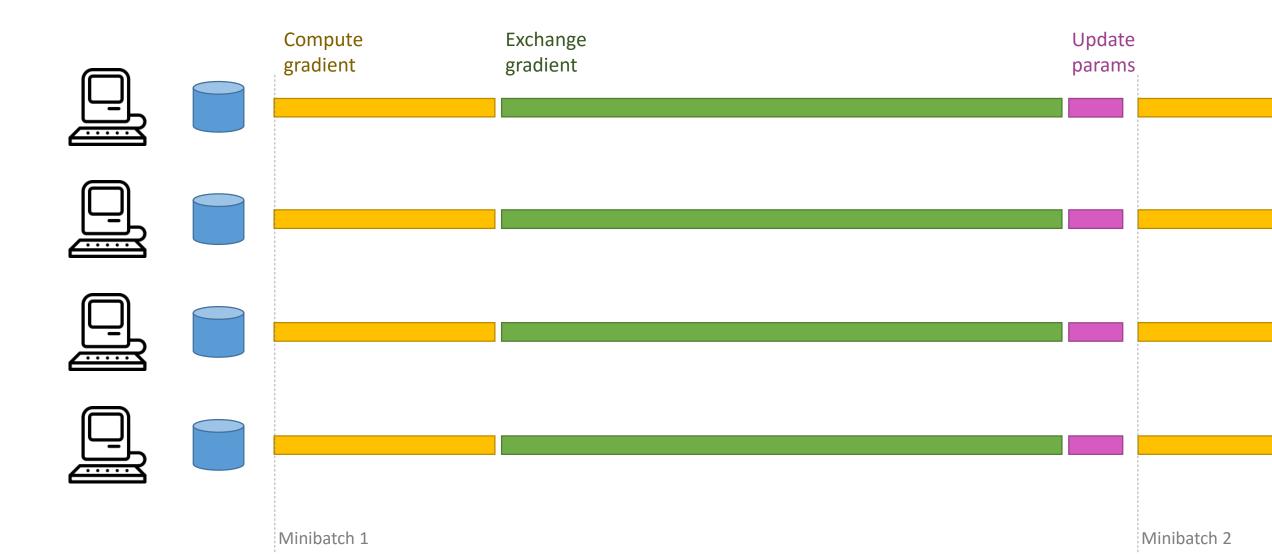
Data parallel SGD



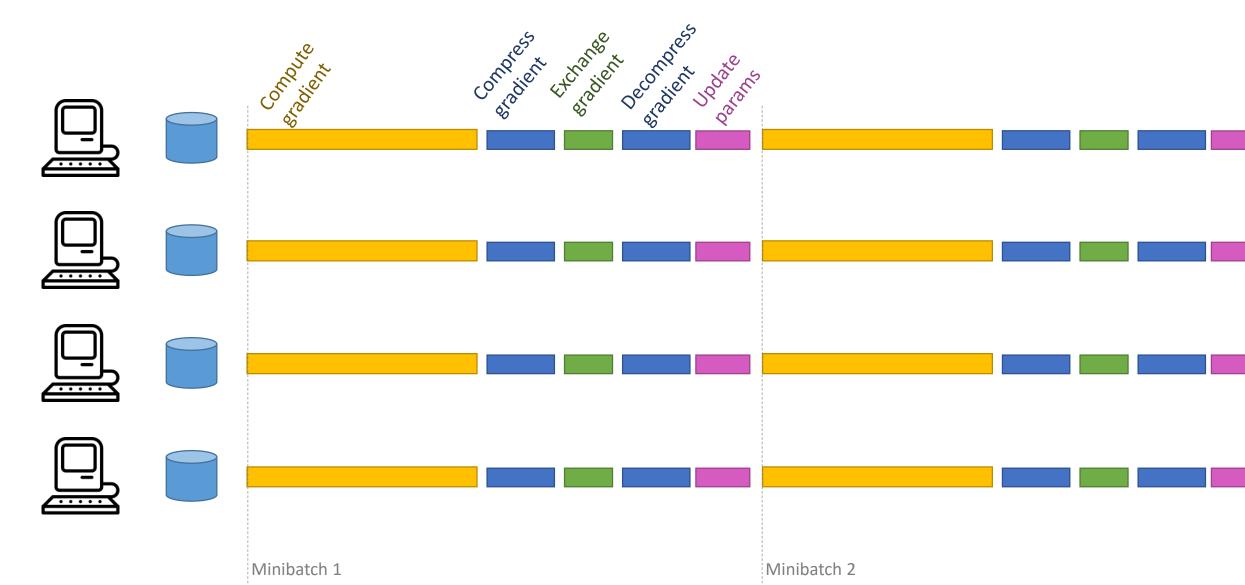
Data parallel SGD (bigger model)



Data parallel SGD (biggggger model)



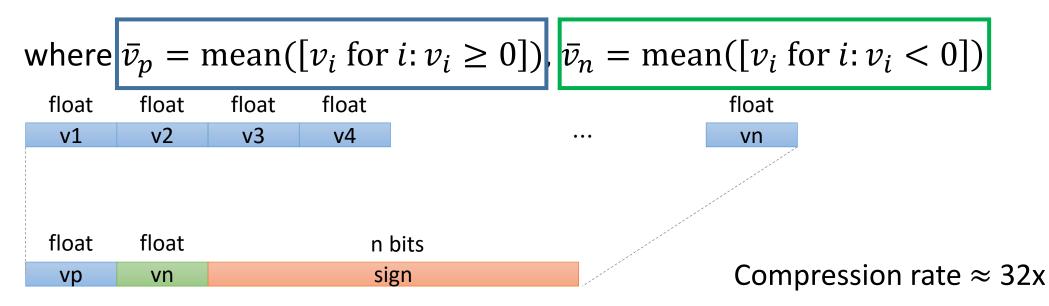
If we could *compress* the gradients...



Inspiration: 1-bit SGD [Seide et al 2014]

Quantization function

$$Q_i[v] = \begin{cases} \bar{v}_p & \text{if } v_i \ge 0, \\ \bar{v}_n & \text{otherwise} \end{cases}$$



Unfortunately, no theoretical justification!

Seide et al (2014) "1-Bit Stochastic Gradient Descent and its Application to Data-Parallel Distributed Training of Speech DNNs"

Our contribution

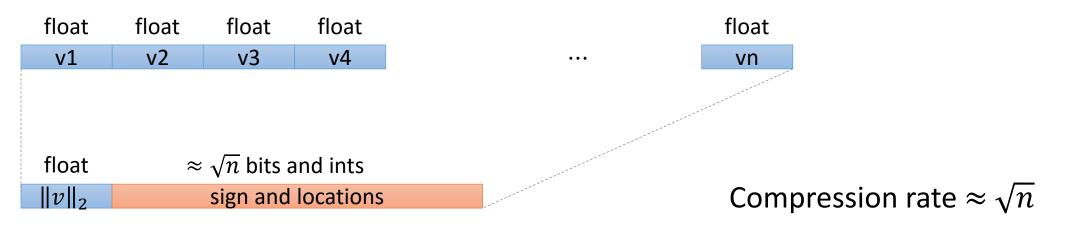
- We propose a (family of) new quantization function
 - Unbiased stochastic gradient
 - Allows super-constant $\tilde{O}(\sqrt{n})$ compression rate \bigcirc
 - Convergence guarantee in $\tilde{O}(\sqrt{n})$ more steps \mathfrak{S}
 - Hyper-parameters control trade-off between convergence and compression
- We empirically show that the convergence does not slow-down too much

A simple randomized quantization function

Quantization function

$$Q_i[v] = \|v\|_2 \cdot \operatorname{sgn}(v_i) \cdot \xi_i(v)$$

where $\xi_i(v) = 1$ with probability $|v_i|/||v||_2$ and 0 otherwise.



Note that $E[\sum_{i} \xi_{i}(v)] \le ||v||_{1}/||v||_{2} \le \sqrt{n}$

Properties of the proposed quantization function

• Quantization function

$$Q_i[v] = \|v\|_2 \cdot \operatorname{sgn}(v_i) \cdot \xi_i(v)$$

where $\xi_i(v) = 1$ with probability $|v_i|/||v||_2$ and 0 otherwise.

1. Sparsity:

$$E\left[\sum_{i} \xi_{i}(v)\right] \leq \|v\|_{1}/\|v\|_{2} \leq \sqrt{n}$$

2. Unbiasedness:

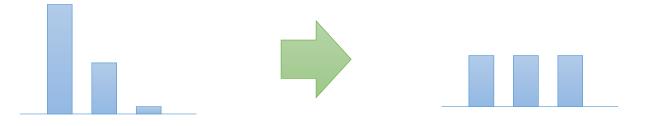
$$E[Q_i[v]] = v_i$$

3. Second moment bound:

 $E[||Q[v]||^2] = \sqrt{n} ||v||^2$

Why this is a better quantization

1-bit SGD approximates large and tiny coordinates to the same mean value



• The proposed quantization function avoids this by randomizing



Theorem

• The quantized gradient can be communicated in

 $F + \sqrt{n}(\log n + \log 2e)$

bits in expectation

- F is the number of bits to represent one float number
- There are only \sqrt{n} non-zero coordinates in expectation
- For each non-zero entry we use O(log(n)) bits to encode the location and 1 bit to encode the sign
- \sqrt{n} times reduction in per iteration communication

Bucketing

- Apply the quantization for every consecutive d coordinates (n/d buckets in total)
 - Bucket size *d*=1 corresponds to no quantization
 - Reduced second moment bound => faster convergence

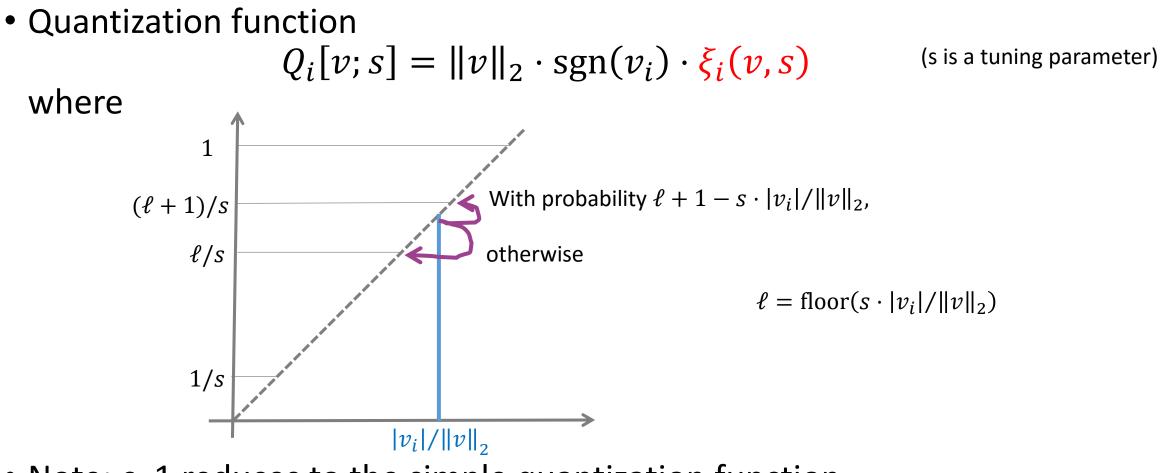
 $E[||Q_d[v]||^2] = \sqrt{d} ||v||^2$

• Communication cost

$$\frac{n}{d} \cdot \left(F + \sqrt{d} (\log d + \log 2e) \right)$$

Bucket 1	Bucket 2	•••	Bucket n/d
d	d		d

Generalized quantization sheme



• Note: *s*=1 reduces to the simple quantization function.

Properties of the generalized quantization scheme

- Quantization function $Q_i[v;s] = \|v\|_2 \cdot \operatorname{sgn}(v_i) \cdot \xi_i(v,s)$ • Properties
 - 1. Sparsity

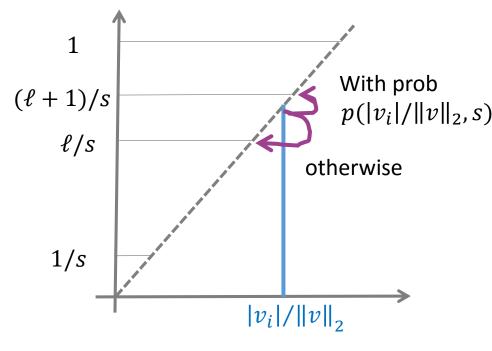
 $E[\|\xi(v,s)\|_0] \le s^2 + \sqrt{n}$

2. Unbiasedness

 $E[Q_i[v;s]] = v_i$

3. Second moment bound

$$E[\|Q[v;s]\|_{2}^{2}] \leq \left(1 + \min\left(\frac{n}{s^{2}}, \frac{\sqrt{n}}{s}\right)\right) \cdot \|v\|_{2}^{2} \qquad (\text{Only } 2\|v\|_{2}^{2} \text{ for } s = \sqrt{n})$$



 $\ell = \text{floor}(s \cdot |v_i| / \|v\|_2)$

Sublinear Theorem (for small s)

• In expectation, the quantized gradient can be communicated in

$$F + \left(3 + \frac{3}{2} \cdot \left(1 + o(1)\right) \log\left(\frac{2 \cdot (s^2 + n)}{s^2 + \sqrt{n}}\right)\right) \cdot (s^2 + \sqrt{n})$$

bits

- Communicate the difference of non-zero locations (at most $s^2 + \sqrt{n}$)
- Use Elias recursive coding
- Magnitude can be encoded by log (power per dimension)
- Recovers the simple case for s=1.

Linear Theorem (for large s)

• In expectation, the quantized gradient can be communicated in

$$F + \left(\frac{1+o(1)}{2}\left(\log\left(1+\frac{s^2+\min(n,s\sqrt{n})}{n}\right)+1\right)+2\right) \cdot n$$

bits

- Don't communicate the locations
- For $s = \sqrt{n}$, we have the bound

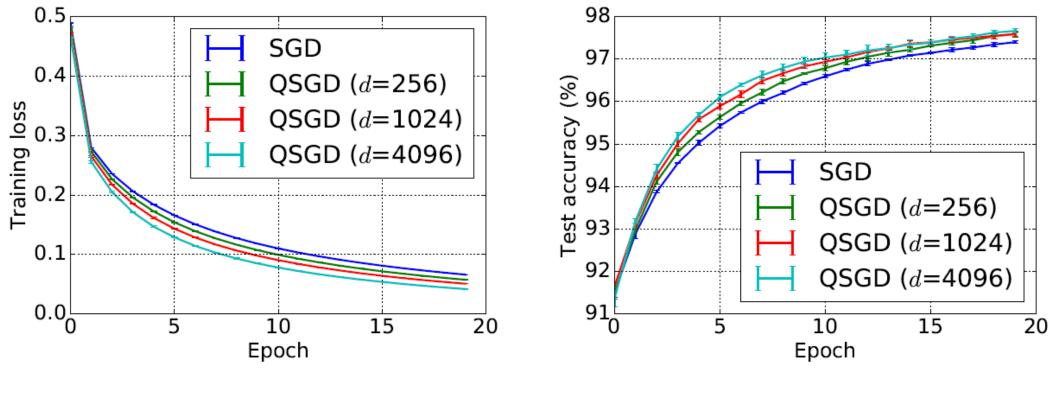
F + 2.8n

• Linear in dimension *n* but much smaller constant 2.8 compared to uncompressed float (32 bits) and second moment only 2 times worse.

Experiments

MNIST (digit recognition task)

- Two-layer Network (non-convex!):
 - Input 784 -> hidden 4096 -> output 10
- Used the simple quantization scheme with bucketing (bucket size: d)

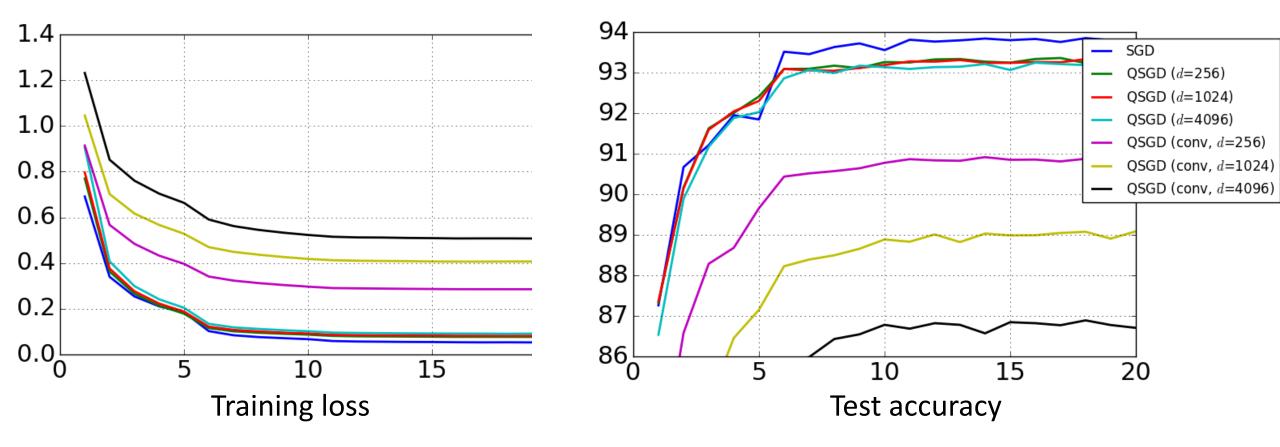


(a) MNIST training loss

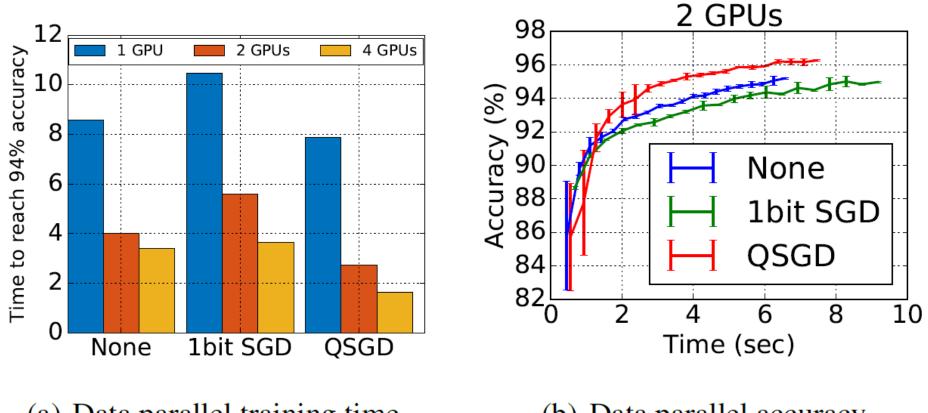
(b) MNIST test accuracy

CIFAR-10 (object recognition task)

- Convolutional network (a small VGG network), 12 layers
 - Input → Conv → BN → Conv → BN → ... → Hidden 4096 → Hidden 4096 → Hidden 4096 → Output 10



Parallelization (preliminary)



(a) Data parallel training time

(b) Data parallel accuracy

Conclusion

- Simple, easy-to-implement quantization scheme
 - Sublinear (\sqrt{n}) number of bits per iteration
 - Performance guarantee
 - Bucketing to control compression / convergence trade-off
- General quantization scheme
 - Requires roughly 3 bits per coordinate and convergence guarantee only 2 times worse compare to SGD

Generalized quantization sheme

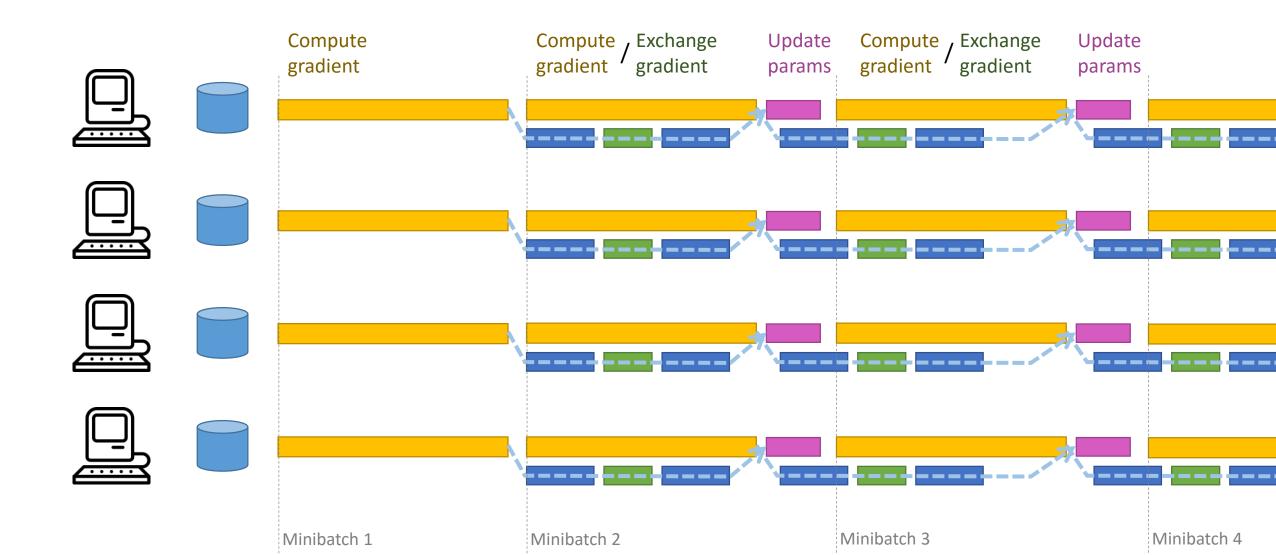
• Quantization function $Q_i[v;s] = \|v\|_2 \cdot \text{sgn}(v_i) \cdot \xi_i(v,s)$ where

$$\xi_i(v,s) = \begin{cases} \ell/s & \text{with probability } \ell + 1 - s \cdot |v_i| / \|v\|_2, \\ (\ell+1)/s & \text{otherwise,} \end{cases}$$

with $\ell = \text{floor}(s \cdot |v_i| / ||v||_2)$ and s is a hyper-parameter.

• Note: *s*=1 reduces to the simple quantization function.

Double buffering



Thanks

Streamline icons